

10.4: The Cross Product of Two Vectors in Space

- A. Many applications in physics, engineering, and geometry involving find a vector in space that is orthogonal to two given vectors. The cross product of two vectors produces such a vector. Cross product is also called vector product.

Definition of Cross Product to Two Vectors in Space

Let $\mathbf{u} = u_1\mathbf{i} + u_2\mathbf{j} + u_3\mathbf{k}$ and $\mathbf{v} = v_1\mathbf{i} + v_2\mathbf{j} + v_3\mathbf{k}$ be vectors in space. The **cross product of \mathbf{u} and \mathbf{v}** is the vector

$$\mathbf{u} \times \mathbf{v} = (u_2v_3 - u_3v_2)\mathbf{i} - (u_1v_3 - u_3v_1)\mathbf{j} + (u_1v_2 - u_2v_1)\mathbf{k}$$

A convenient way to calculate the cross product is to use the following determinant form.

$$\mathbf{u} \times \mathbf{v} = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ u_1 & u_2 & u_3 \\ v_1 & v_2 & v_3 \end{vmatrix}$$

- B. **Theorem 10.7: Algebraic Properties of the Cross Product** See Page 745

C. Geometric Properties of the Cross Product

Let \mathbf{u} and \mathbf{v} be nonzero vectors in space, and let θ be the angle between \mathbf{u} and \mathbf{v} .

1. $\mathbf{u} \times \mathbf{v}$ is orthogonal to both \mathbf{u} and \mathbf{v} .
2. $\|\mathbf{u} \times \mathbf{v}\| = \|\mathbf{u}\| \|\mathbf{v}\| \sin \theta$
3. $\mathbf{u} \times \mathbf{v} = \mathbf{0}$ if and only if \mathbf{u} and \mathbf{v} are scalar multiples of each other.
4. $\|\mathbf{u} \times \mathbf{v}\| =$ area of parallelogram having \mathbf{u} and \mathbf{v} as adjacent sides.

Note: The cross product $\mathbf{u} \times \mathbf{v}$ is perpendicular to each of \mathbf{u} and \mathbf{v} . It's direction is given by the thumb of the right hand when your fingers rotate from \mathbf{u} to \mathbf{v} .

- D. In physics, the cross product can be used to measure **torque** – **the moment \mathbf{M} of a force \mathbf{F} about a point \mathbf{P}** . If the point of application of the force is Q , the moment \mathbf{M} about P is given by

$$\mathbf{M} = \overline{PQ} \times \mathbf{F}$$

The magnitude of the moment \mathbf{M} measures the tendency of the vector \overline{PQ} to rotate counterclockwise (using the right-hand rule) about an axis directed along the vector \mathbf{M} .

E. Theorem 10.9: The Triple Scalar Product

For $\mathbf{u} = u_1\mathbf{i} + u_2\mathbf{j} + u_3\mathbf{k}$ and $\mathbf{v} = v_1\mathbf{i} + v_2\mathbf{j} + v_3\mathbf{k}$ and $\mathbf{w} = w_1\mathbf{i} + w_2\mathbf{j} + w_3\mathbf{k}$, the triple scalar product is given by

$$\mathbf{u} \cdot (\mathbf{v} \times \mathbf{w}) = \begin{vmatrix} u_1 & u_2 & u_3 \\ v_1 & v_2 & v_3 \\ w_1 & w_2 & w_3 \end{vmatrix}$$

F. Theorem 10.10: Geometric Property of Triple Scalar Product

The volume V of a parallelepiped with vectors \mathbf{u} , \mathbf{v} , and \mathbf{w} as adjacent edges is given by

$$V = |\mathbf{u} \cdot (\mathbf{v} \times \mathbf{w})|$$