Appendix E: Rotation and the General Second-Degree Equation

A. Theorem A.1 – Rotation of Axes The general equation of the conic $Ax^{2} + Bxy + Cy^{2} + Dx + Ey + F = 0$

where B \neq 0, can be rewritten as A'(x')² + C'(y')² + D'x'+ E'y'+ F' = 0

by rotating the coordinate axes through an angle $\boldsymbol{\theta},$ where

$$\cot 2\theta = \frac{A-C}{B}$$

The coefficients of the new equation are obtained by making the substitutions

 $x = x'\cos\theta - y'\sin\theta$ $y = x'\sin\theta + y'\cos\theta$

Proof is in the appendix

We will using the result of the proof to obtain A', B', etc...

$$A' = A\cos^{2} \theta + B\cos \theta \sin \theta + C\sin^{2} \theta$$
$$C' = A\sin^{2} \theta - B\cos \theta \sin \theta + C\cos^{2} \theta$$
$$D' = D\cos \theta + E\sin \theta$$
$$E' = -D\sin \theta + E\cos \theta$$
$$F' = F$$

Examples: 6, 10

B. Theorem A.2 (optional) Rotation Invariants

C. Theorem A.3 – Classification of Conics by the Discriminant

The graph of $Ax^2 + Bxy + Cy^2 + Dx + Ey + F = 0$ is, except in the degenerate cases, determined by its discriminant as follows.

- 1. Ellipse or Circle B² –
- 2. Parabola
- 3. Hyperbola

 $B^{2} - 4AC < 0$ $B^{2} - 4AC = 0$ $B^{2} - 4AC > 0$

Examples: 20, 22, 28, 30