Section 9.2: Plane Curves and Parametric Equations

A. Definition of a Plane Curve

If f and g are continuous functions of t on an interval I, then the equations

x = f(t) and y = g(t)

are called parametric equations and t is called the parameter. Taken together, the parametric equations, and the graph are called a plane curve, denoted by C.

By plotting points in order of increasing values of t, the curve is traced out in a specific direction. This is called the orientation of the curve.

B. Rewriting a parametric equation as a rectangular equation is called eliminating the parameter.

- 1. Solve for t in one of the equations.
- 2. Substitute into the second equation.
- 3. Simply.
- The Domain may need to be adjusted based upon the original parametric equation
- Trigonometry might need to be used. Examples: 4, 10, 16, 24

C. Finding parametric equations from rectangular equations.

- 1. Parametric equations are not unique.
- 2. Usually let x = t and then replace x with t in the rectangular equation.

 For a line through (x₁,y₁) and (x₂,y₂) x = x₁ + t(x₂ - x₁) and y = y₁ + t(y₂ - y₁)
For a circle: x = h + r cos θ and y = k + r sin θ Examples: 44, 46

D. Definition of a Smooth Curve

A curve represented by x = f(t) and y = g(t) is called smooth if f' and g' are continuous on I and not simultaneously 0. The curve is called piecewise smooth if it is smooth on each subinterval or some partition of I.

E. Cycloid: The path down which a particle will slide from point A to point B in the shortest time is an inverted cycloid passing through points A and B. The amazing part is that a particle starting at rest at any other point of the cycloid between A and B will take exactly the same time to reach B.

> Equation of a Cycloid $x = a(\theta - \sin \theta)$ $y = a(1 - \cos \theta)$

Example: 56